

# *Validation of Satellite Atmospheric Soundings*

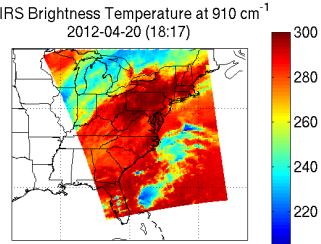
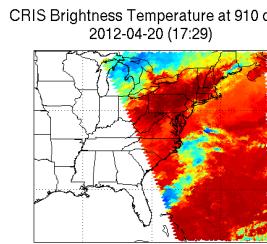
## *The GRASP Campaign*

**W.L. Smith Sr.<sup>1,2</sup>, M.P. McCormick<sup>1</sup>, E. Weisz<sup>2</sup>, M. Yesalusky, N. Boyouk<sup>1</sup>, J. Geasey<sup>1</sup>, M. Howard<sup>3</sup>, A. Larar<sup>5</sup>, K. Leavor<sup>1</sup>, R. Lee<sup>1</sup>, H. Revercomb<sup>2</sup>, L. Rochette<sup>4</sup>, C. Spells<sup>1</sup>, J. Su<sup>1</sup>, and J. Yongxiao<sup>1</sup>**

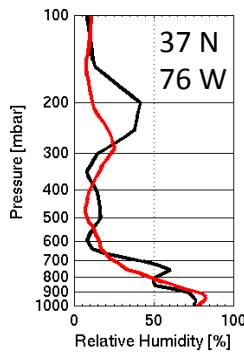
<sup>1</sup> Hampton University, <sup>2</sup> University of Wisconsin – Madison,

<sup>3</sup> National Security Technologies, <sup>4</sup> LR Technologies, <sup>5</sup> NASA Langley Research Center

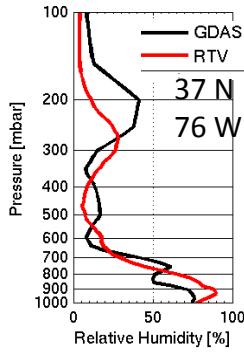
### Satellites



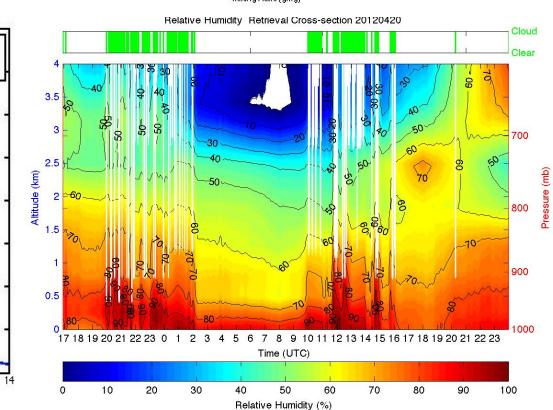
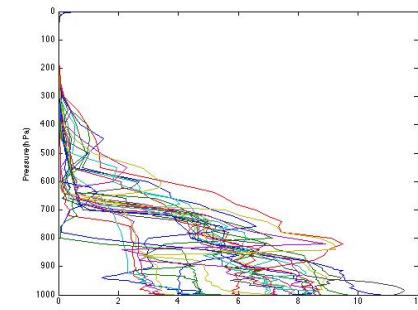
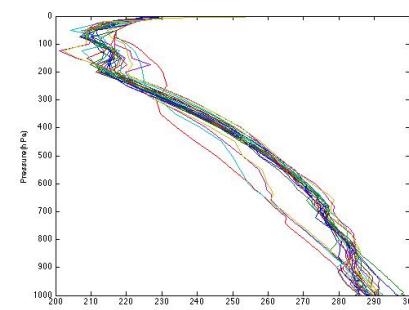
**CrIS-17:30**



**AIRS-18:17 UT**



### Radiosondes

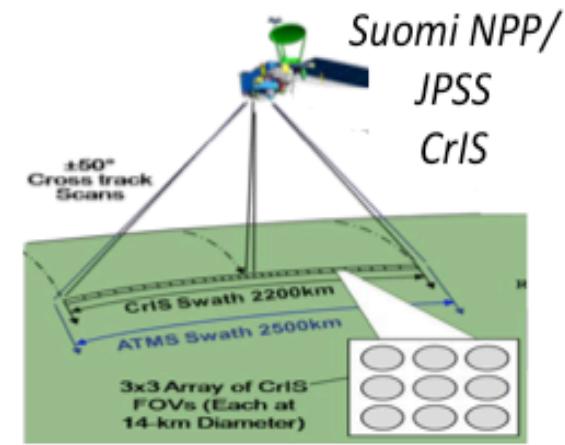
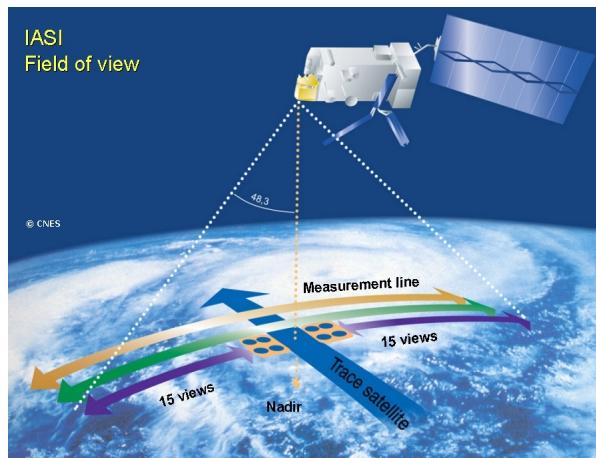
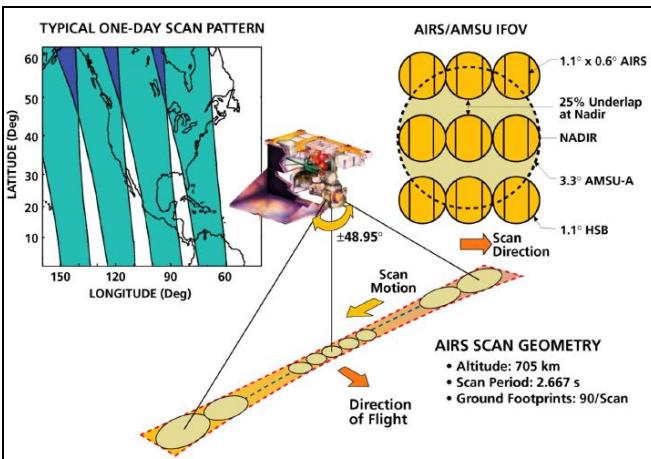


### Models

### Raman Lidar

### Ground based FTS

# Satellite Ultraspectral Sounders



- Grating Spectrometer with resolution of  $0.5 - 2 \text{ cm}^{-1}$  (resolving power of  $\sim 1200$ )
- Spectral range:  $650 - 2700, \text{ cm}^{-1}$  PV and PC HdCdTe focal plane mechanically cooled to 60K
- Focal plane has 4756 detectors, **2378 channels**
- 310 K Blackbody and space view provides radiometric calibration
- NEDT ranges from .05K to 0.5K

**AIRS (2002)**

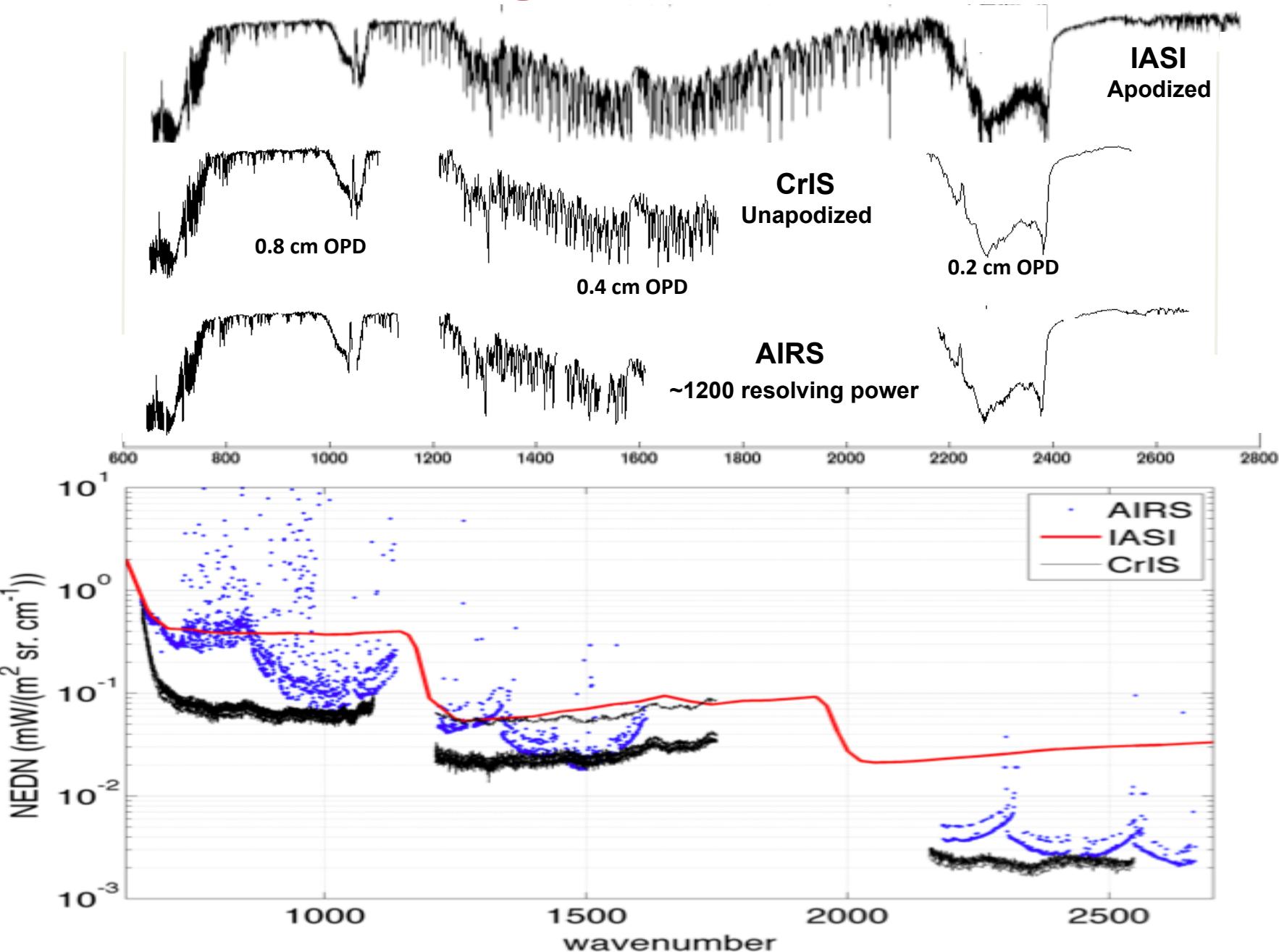
- Michelson Interferometer with resolution of  $0.25 \text{ cm}^{-1}$  (resolving power of 2400-12000)
- Spectral range:  $660 - 2700 \text{ cm}^{-1}$  PV and PC HdCdTe focal planes radiatively cooled to 90K
- Focal plane 12 detectors, **8461 spectral channels**
- 310 K Blackbody and space view provides radiometric calibration
- NEDT:  $0.1 - 0.75 \text{ K}$

**IASI (2006)**

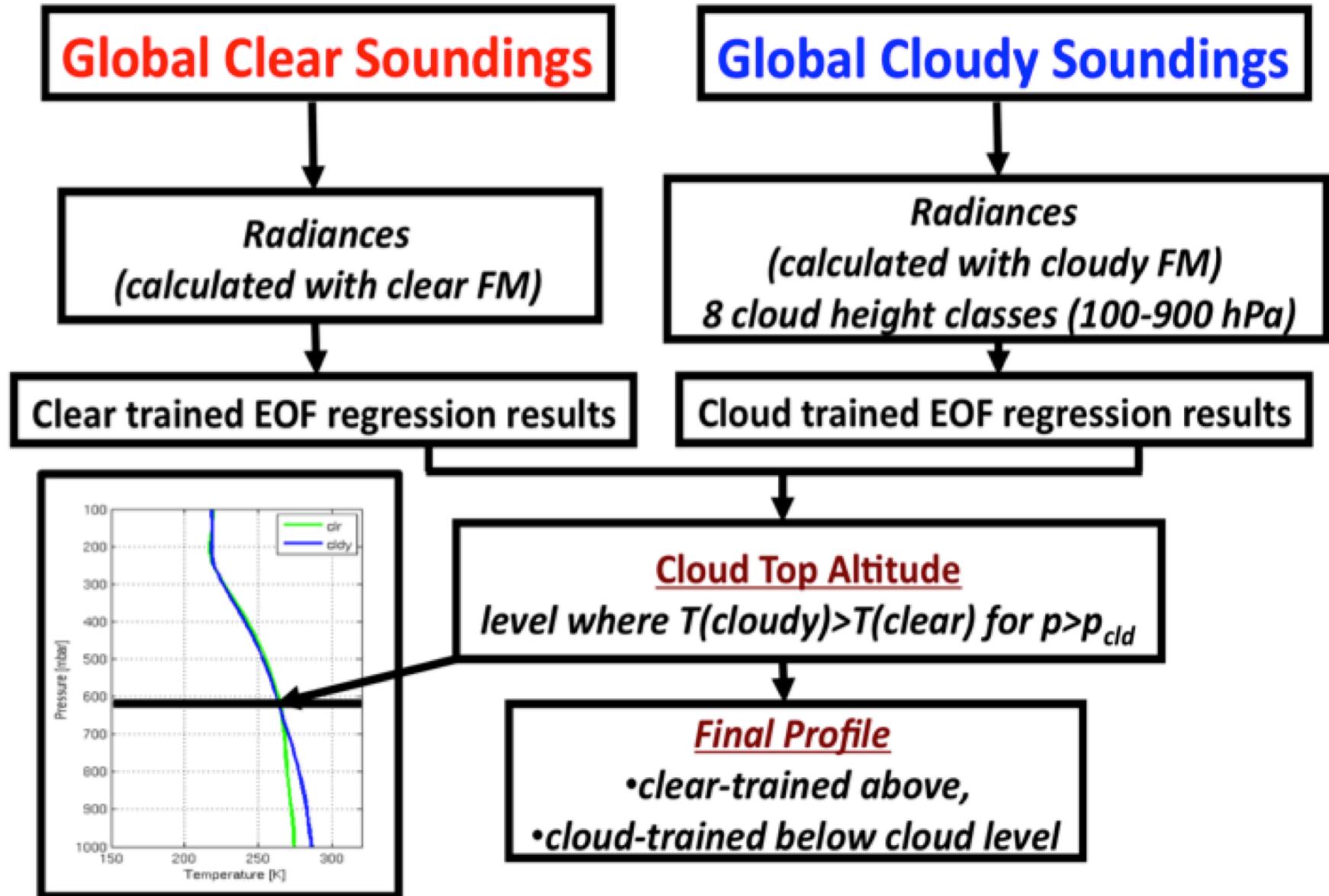
- Michelson Interferometer with resolution of  $0.25 \text{ cm}^{-1}$  (resolving power of 2400-12000)
- Spectral range:  $660 - 2700 \text{ cm}^{-1}$  PV HdCdTe focal planes passively cooled to 85K
- Focal plane 27 detectors, **1305 spectral channels**
- 310 K Blackbody and space view provides radiometric calibration
- NEDT:  $0.05 - 0.5 \text{ K}$

**CrIS (2011)**

# Spectral Coverage, Resolution, and Noise

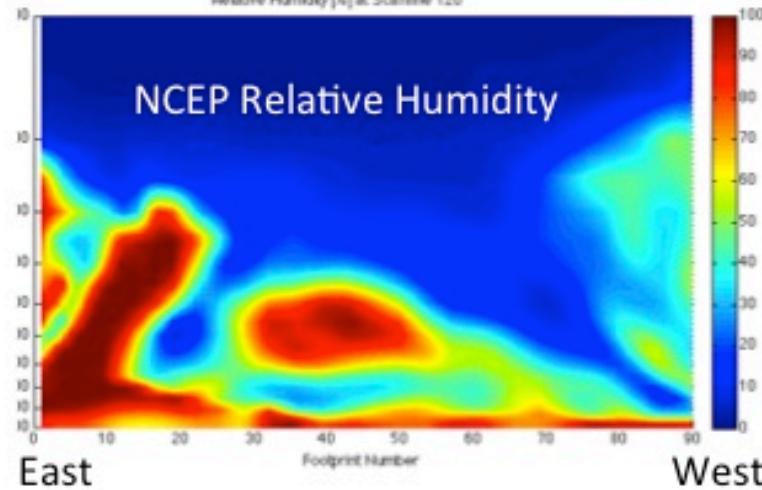
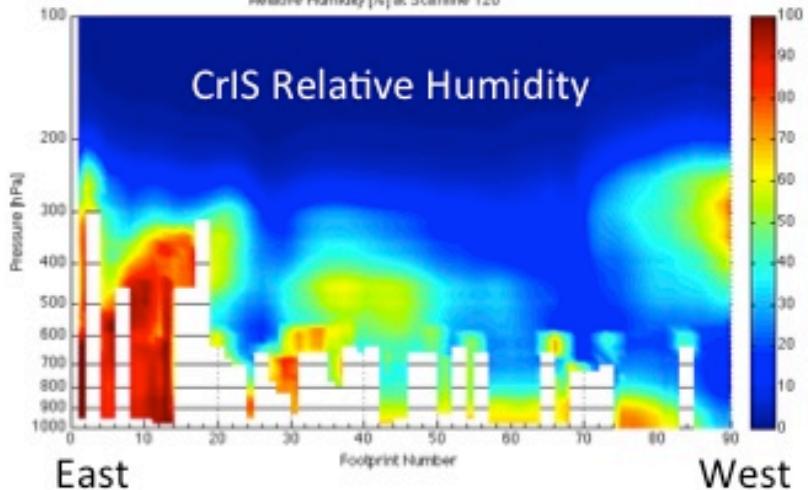
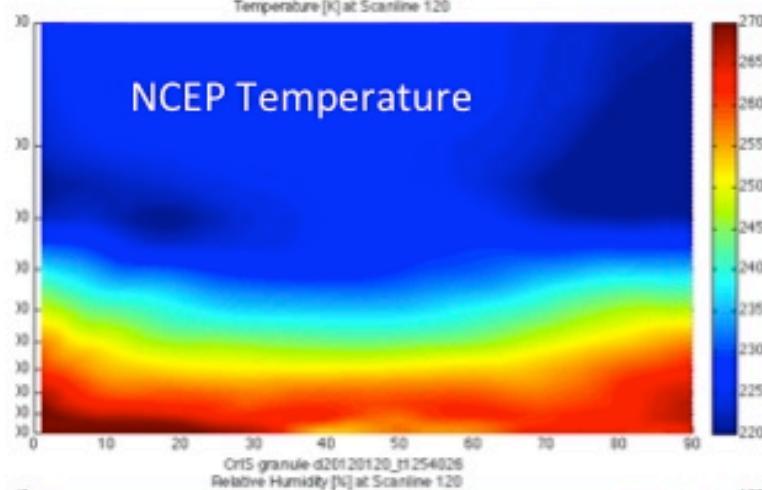
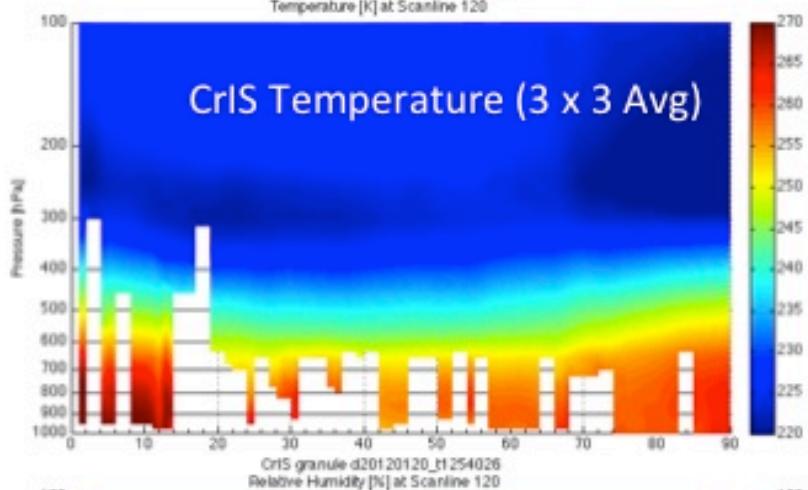
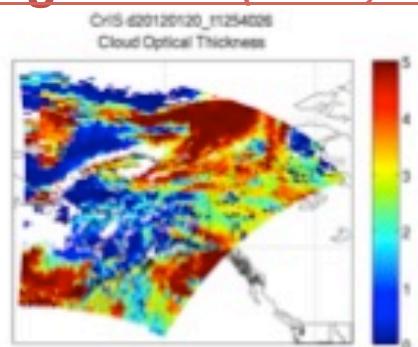
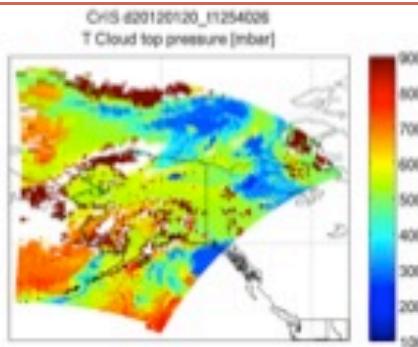
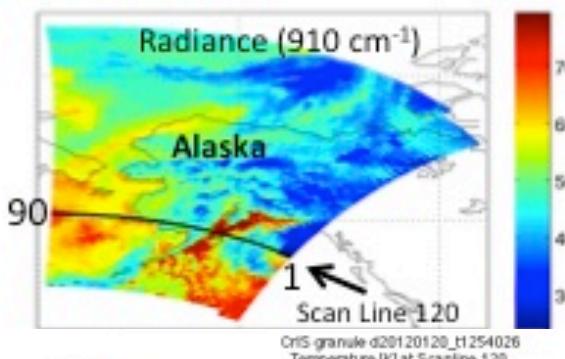


# Dual-Regression Retrieval Method<sup>1</sup>



<sup>1</sup>Smith, W. L., E. Weisz, S. Kirev, D. K. Zhou, Z. Li, and E. E. Borbas, 2012: Dual-Regression Retrieval Algorithm for Real-Time Processing of Satellite Ultraspectral Radiances. *J. Appl. Meteor. Clim.* <http://dx.doi.org/10.1175/JAMC-D-11-0173.1>.

# First CrIS Results Produced with the DR Retrieval Algorithm (Feb 1, 2012)



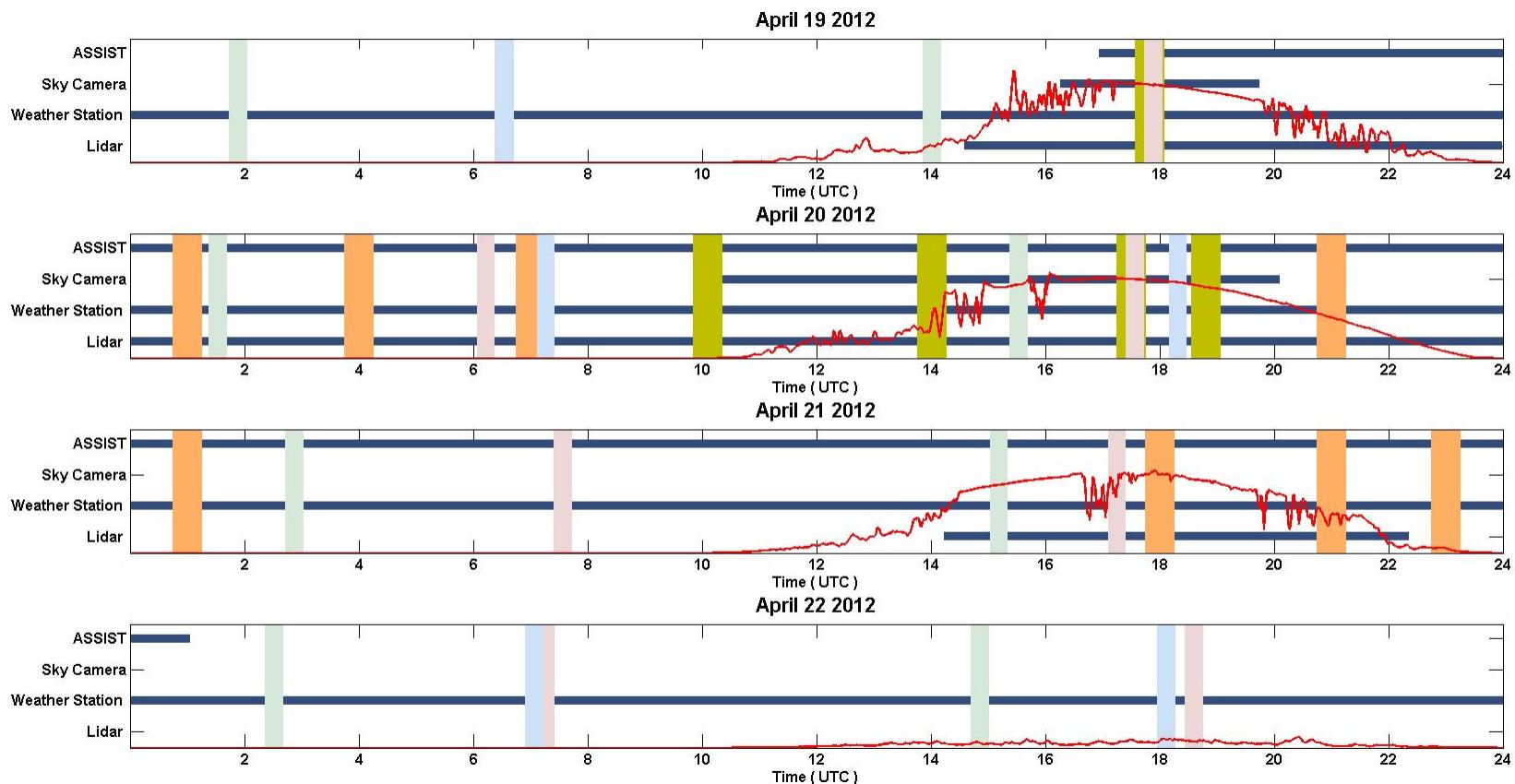
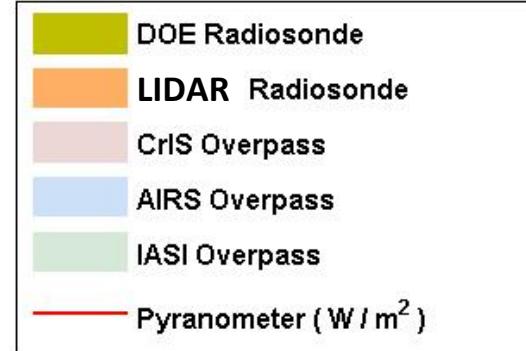
# ***Ground Remote Atmospheric Sounding Project (GRASP)***

## **Validation Campaign ( 16 – 30 April, 2012)**

- ***Profile retrievals*** from all Metop IASI, Aqua AIRS, Suomi NPP CrIS data for orbital tracks within 1000-km of Hampton University( HU), Hampton VA, were processed for validation
- ***Radiosondes*** were launched from HU at satellite overpass times
- Quasi continuous ***upward looking FTS*** measurements were made for determining PBL temperature, moisture, and trace gas structure
- ***Raman LIDAR*** measurements were made for deriving cloud, aerosol, and free troposphere temperature and water vapor profiles
- Continuous measurements of ***surface meteorological and radiative flux parameters*** ( $P$ ,  $T$ ,  $Q$ ,  $V$ , LW Flux, SW Flux) were obtained
- ***All-sky camera*** operated for identifying cloudiness during radiation and meteorological measurements

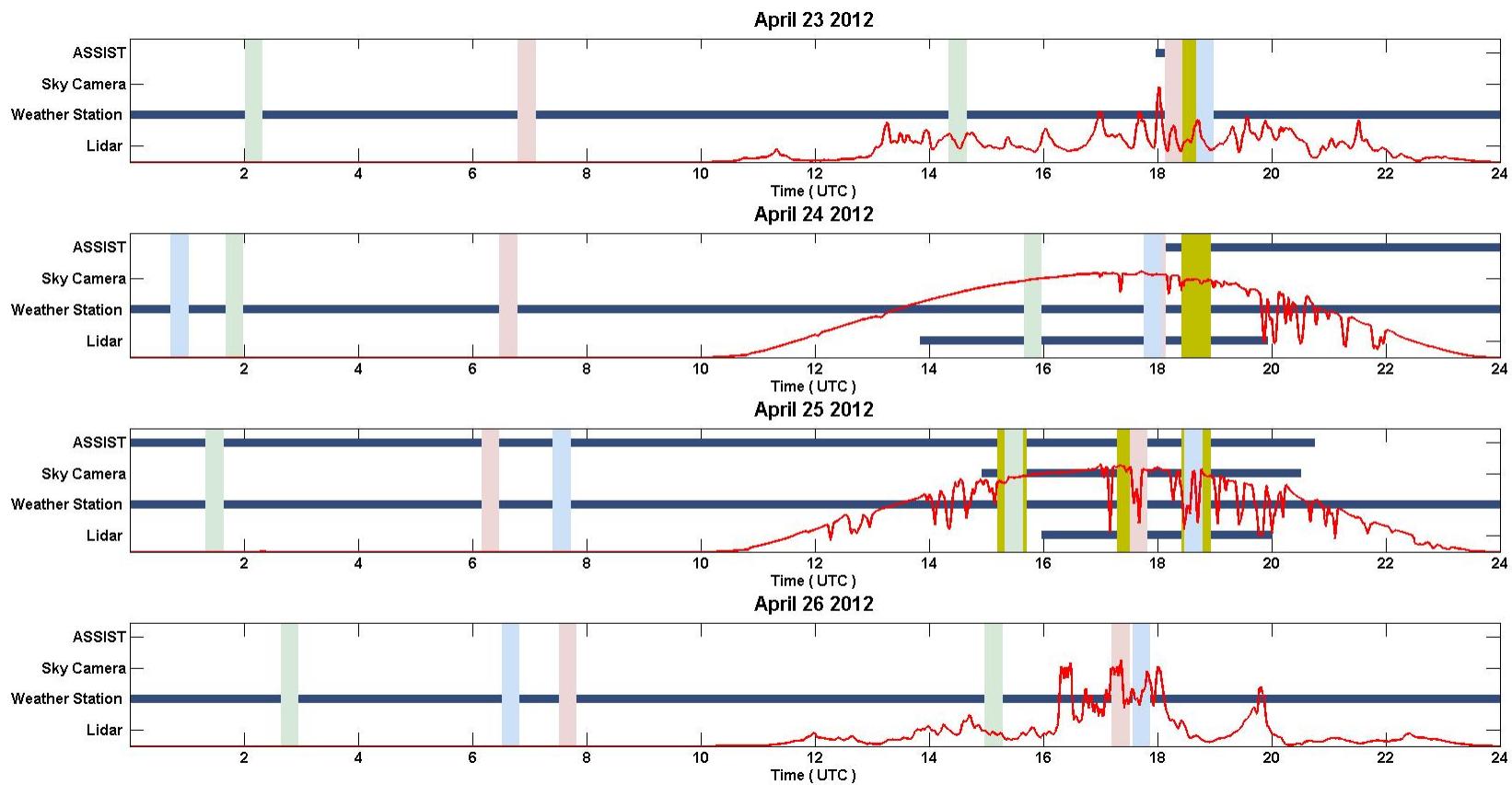
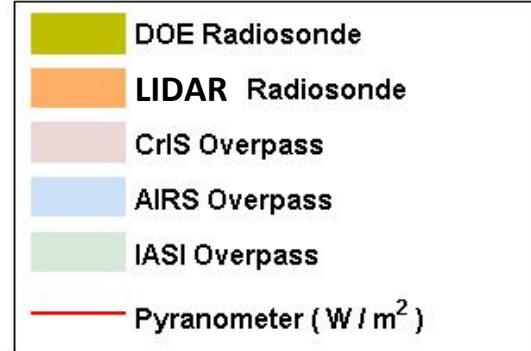
# GRASP

## Measurement Data Availability



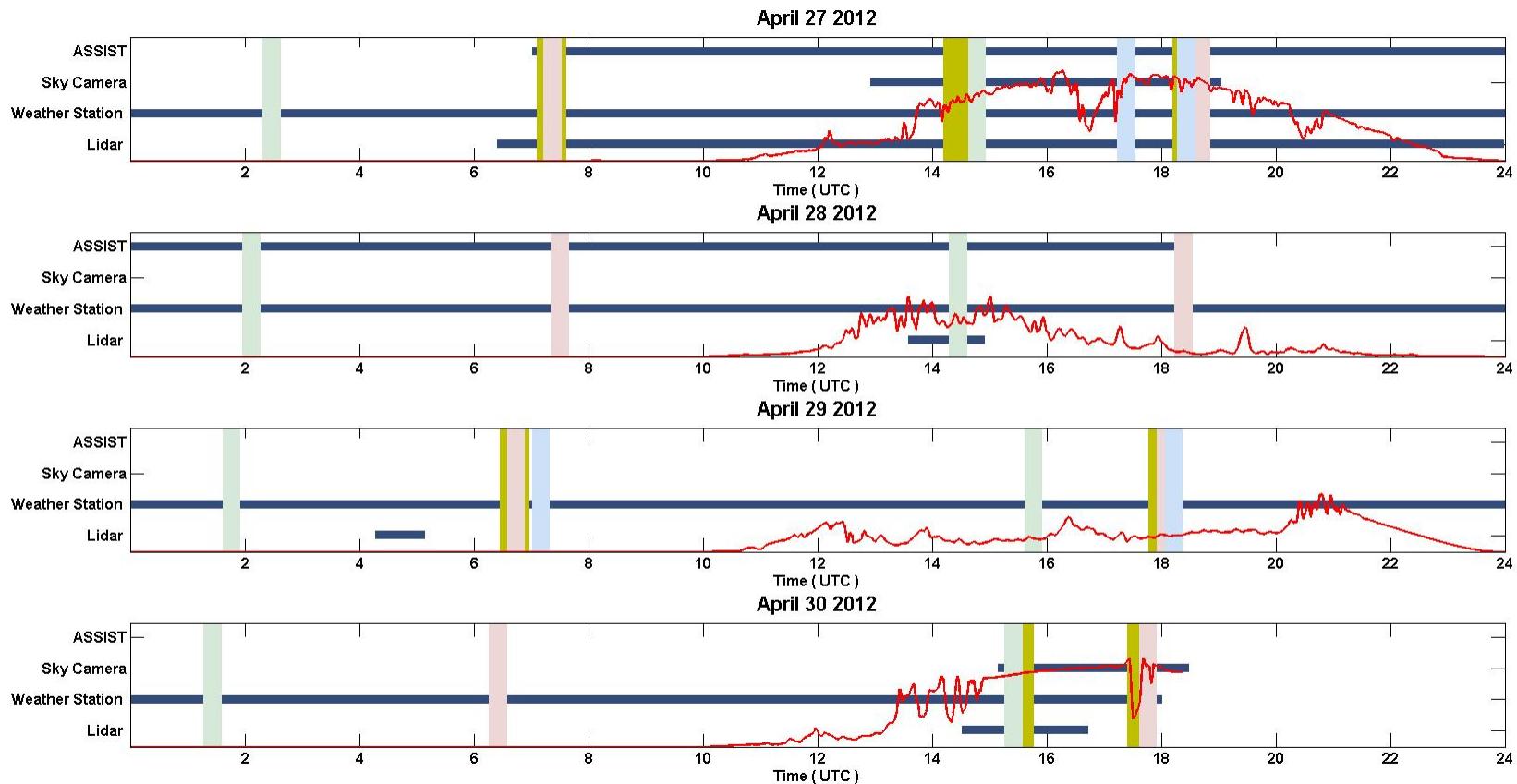
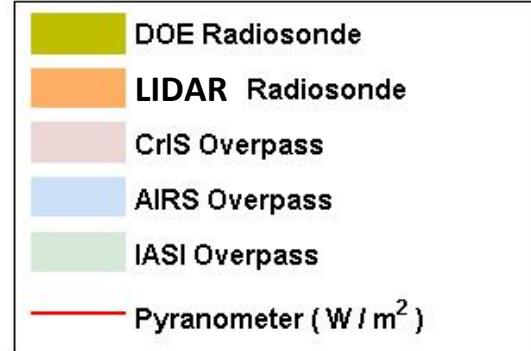
# GRASP

## Measurement Data Availability



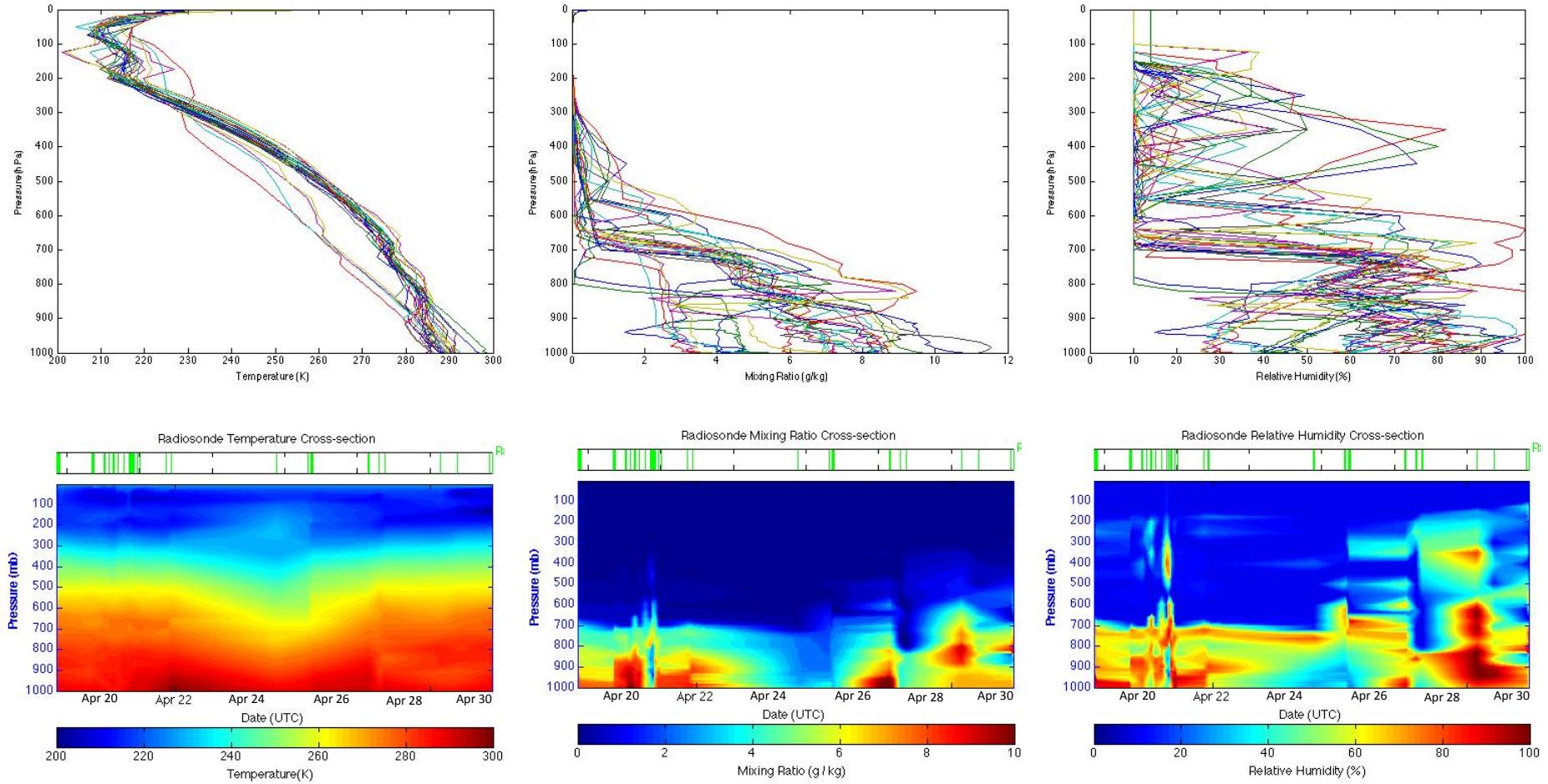
# GRASP

## Measurement Data Availability



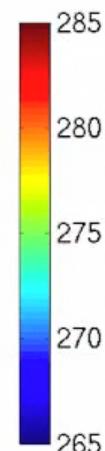
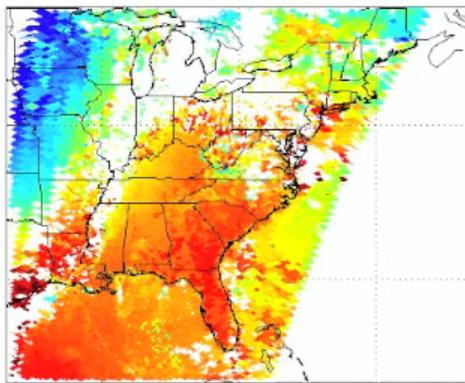
# *GRASP Radiosonde Observations (27)*

## April 19 – April 30, 2012

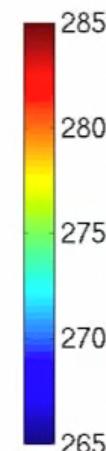
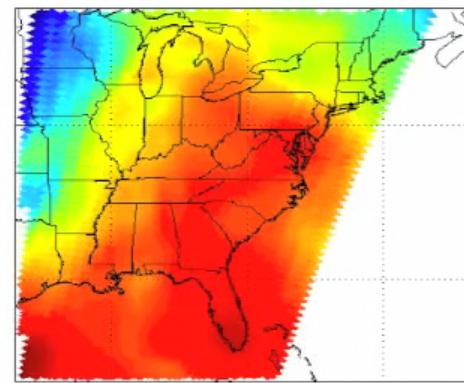


***GRASP Validation Campaign April 2012***  
**AIRS, CrIS, IASI Retrievals**  
**16-22 April, 2012**

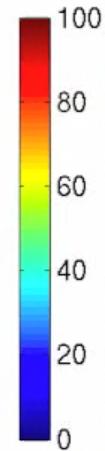
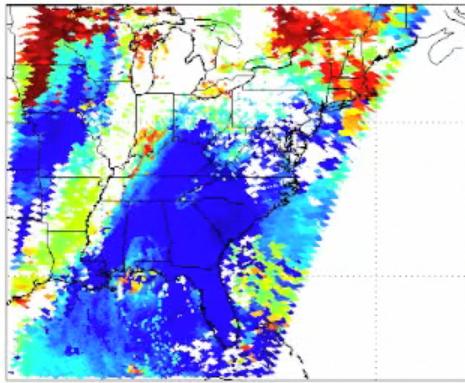
CRIS Temperature [K] at 707 hPa  
2012-04-16 (07:22,07:30)



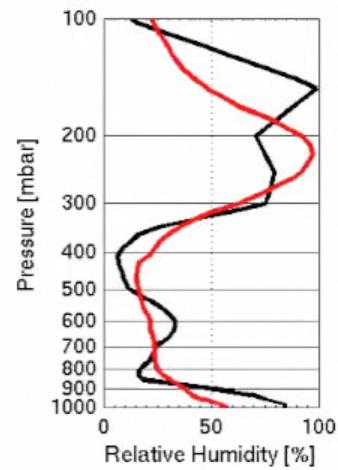
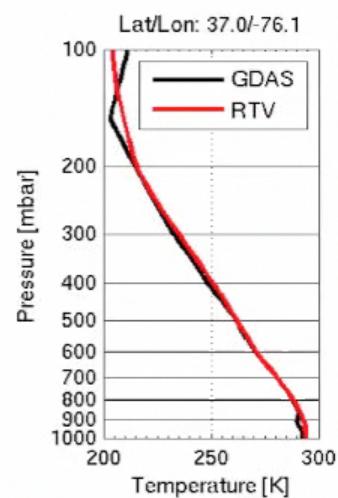
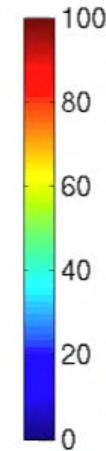
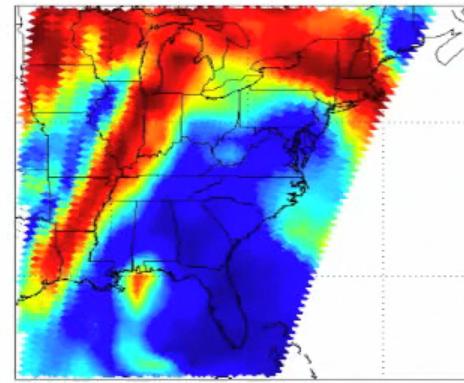
GDAS Temperature [K] at 706.6 hPa  
2012-04-16 (07:22,07:30)



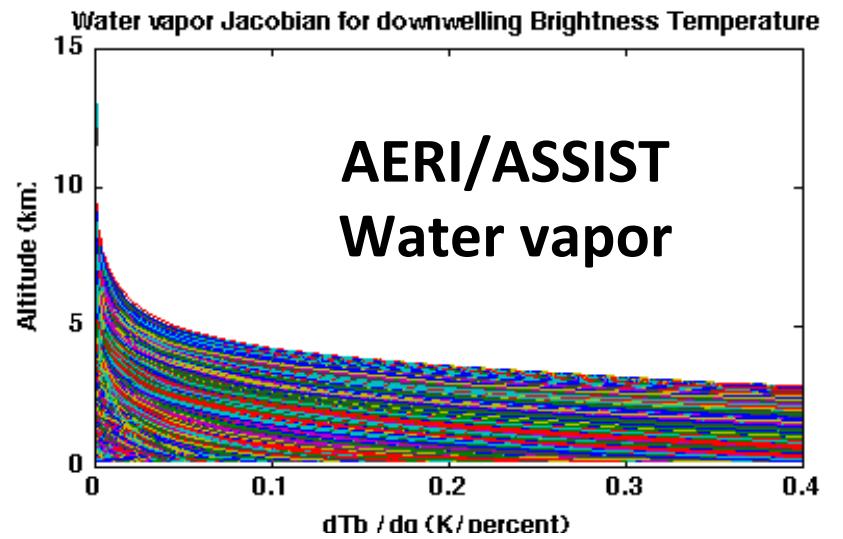
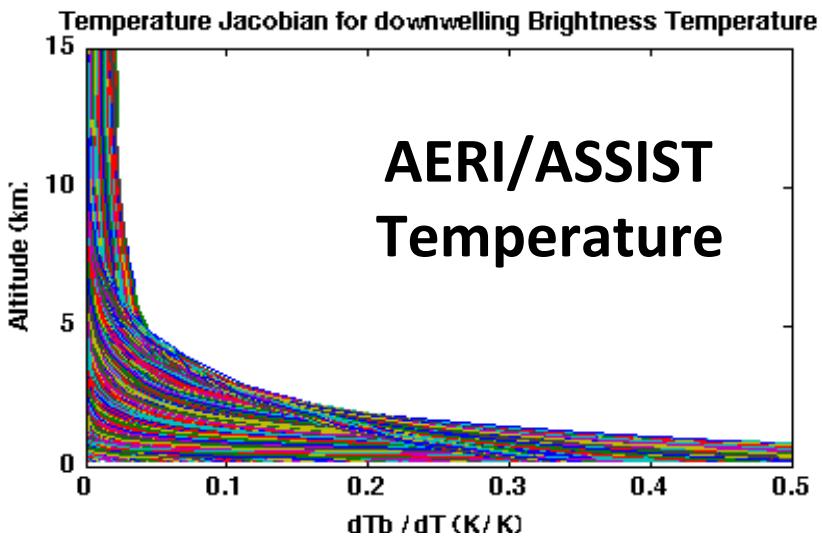
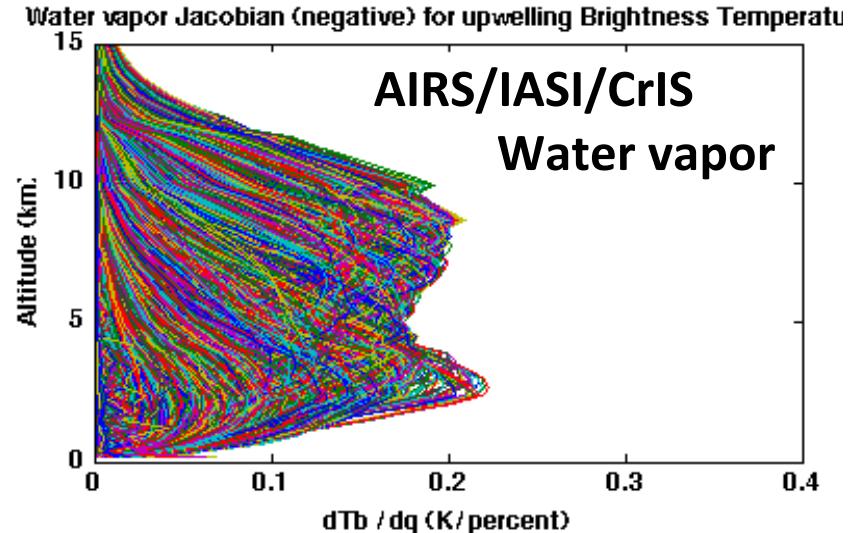
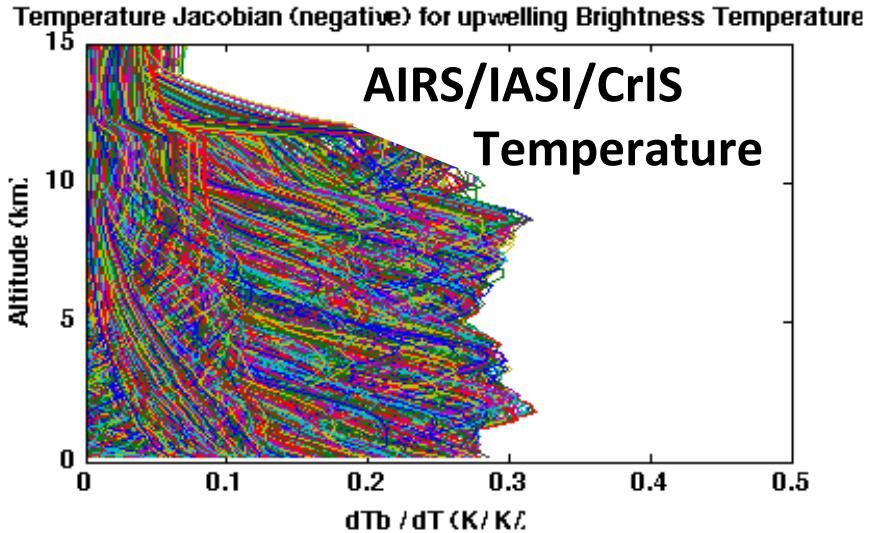
CRIS Relative Humidity [%] at 707 hPa  
2012-04-16 (07:22,07:30)



GDAS Relative Humidity [%] at 707 hPa  
2012-04-16 (07:22,07:30)



# *Satellite Vs Ground-based Profile Sensitivity*



Satellite Information Content is High in the Free-atmosphere  
Ground-based Information Content is High in the Low Atmosphere

# ***Physical Regression (PR) Retrieval Methodology***

$$Q_{\text{ret}} = q_o + (r_m - r_o)C$$

$$C = (R'{}^T R' + \lambda E^T E)^{-1} R'{}^T Q'$$

$q$  = atmospheric profiles (temperature, water vapor, etc.)

$C$  = statistical covariance about the initial profile  $q_o$

$r_o$  = radiance calculated from the initial profile  $q_o$

$Q$  &  $R$  = climatological ensemble of profiles & radiance spectra

( )' = deviation from the initial conditions  $q_o$  and  $r_o$

$E^T E$  = statistical covariance of spectral radiance noise

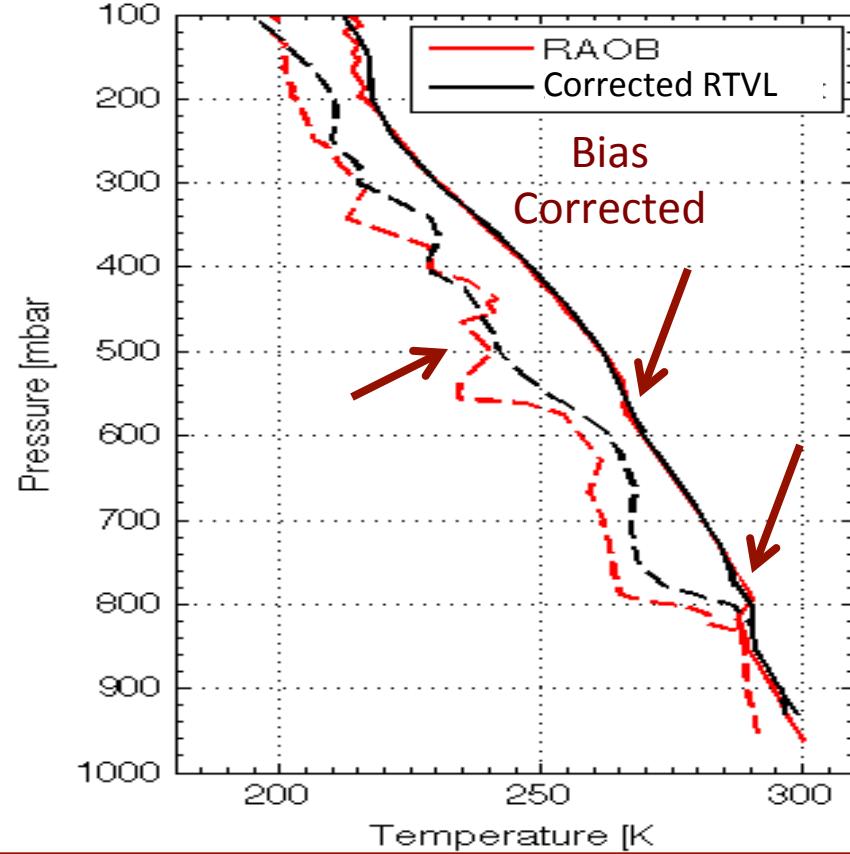
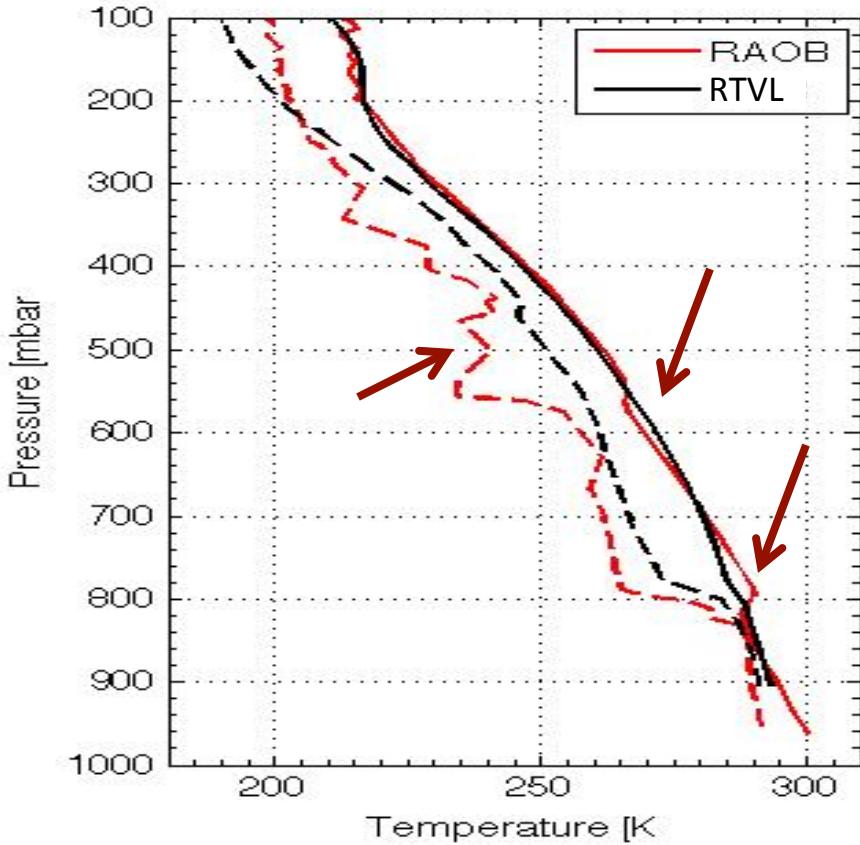
$\lambda$  = scalar determined as that value which minimizes the  
RMS difference between the retrieval calculated radiance  
spectrum and observed radiance spectrum

# BIAS Corrections Using Forecast Model Profile

**Problem:** PR method uses a statistical training data set. Imperfect skill due to lack of vertical resolution in radiances leads to local bias in PR retrievals.

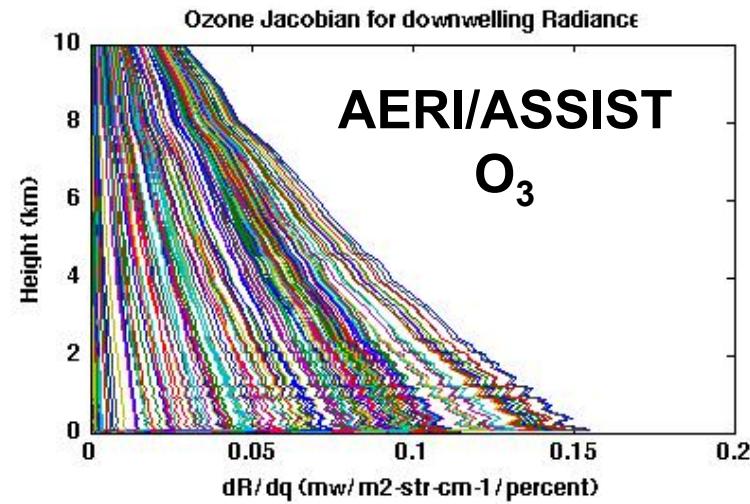
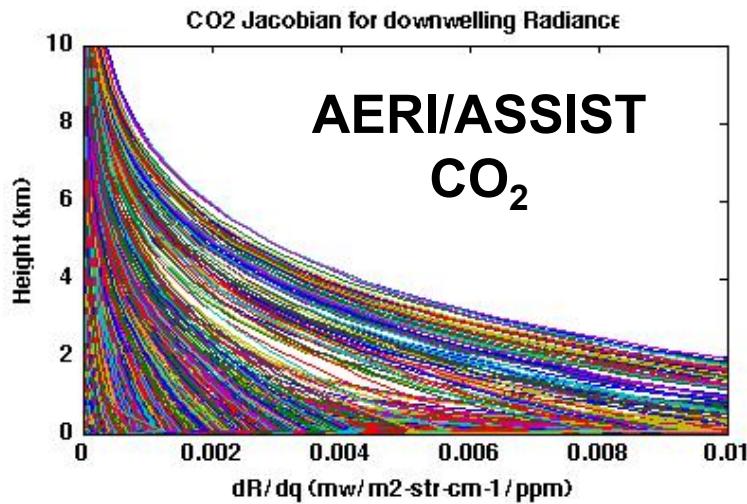
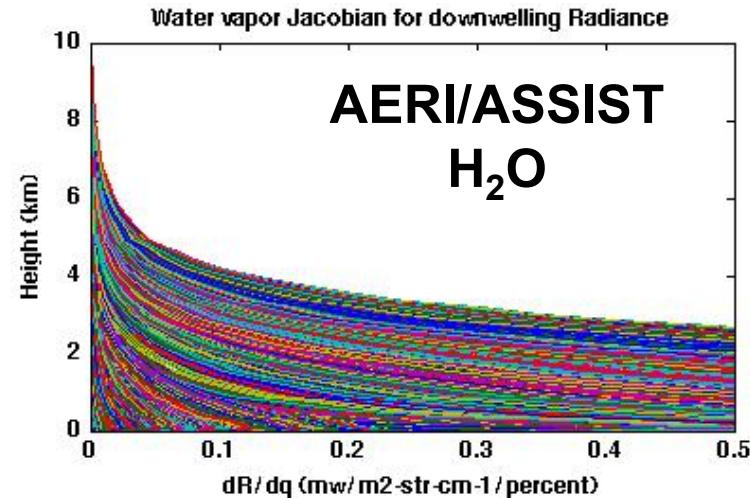
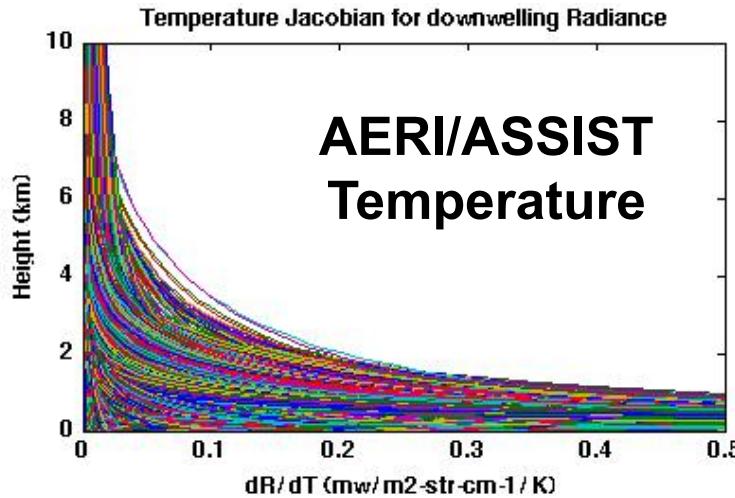
**Solution:** Calculate radiances from forecast model profile (FP) and perform PR retrieval using model radiances.

**Statistical bias correction = FP – FP radiance retrieved FP**



**Bias Correction removes statistical bias with respect to the model FP**

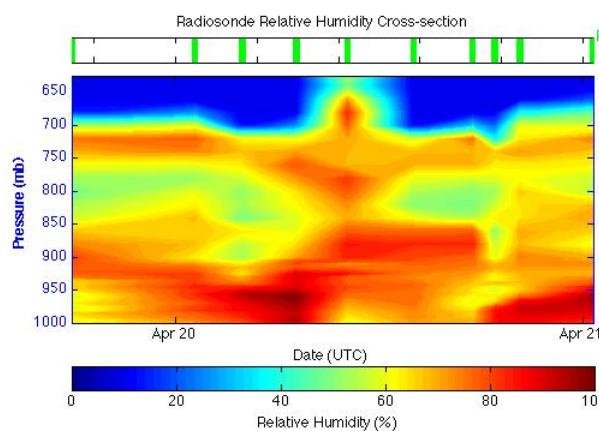
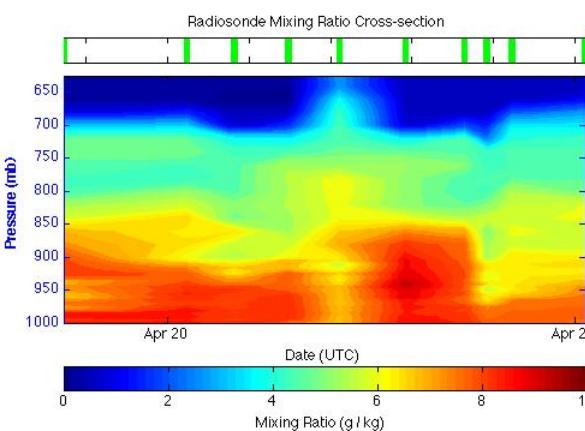
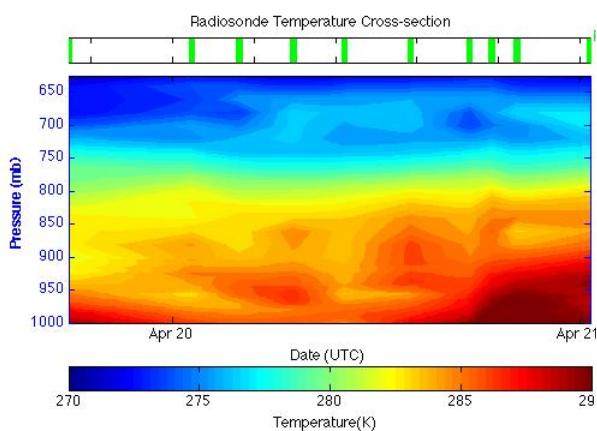
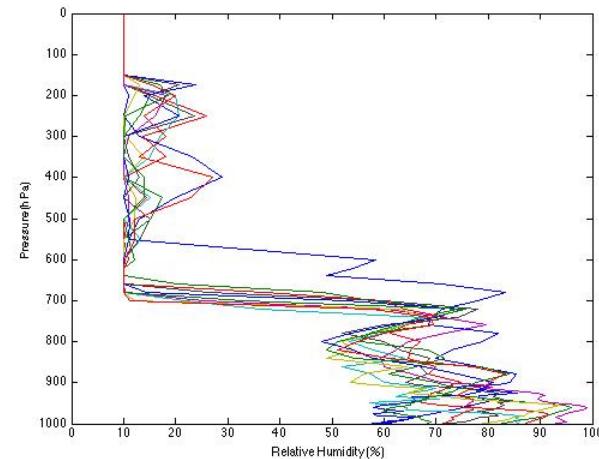
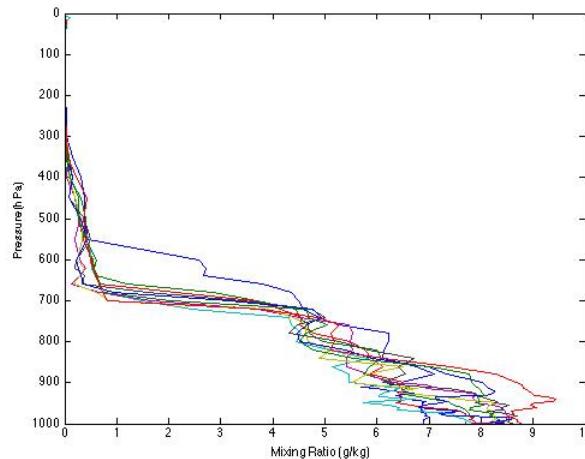
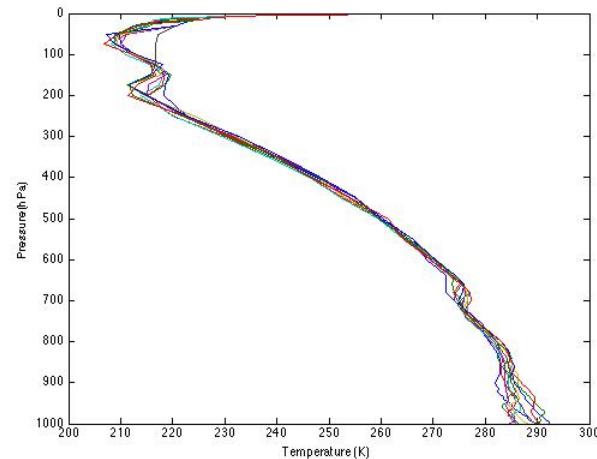
# Ground-based Profile Sensitivity



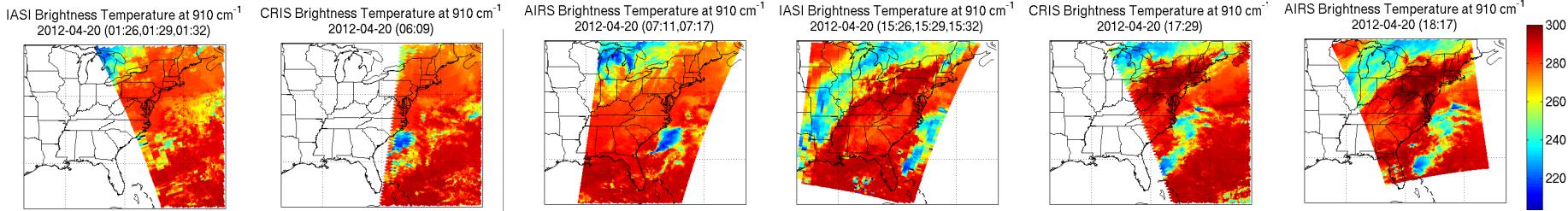
**AERI/ ASSIST measurements are very sensitive to temperature, water vapor, and GHG variations in the lower atmosphere (i.e., 0 – 4-km)**

# ***GRASP "Golden Day" April 20, 2012***

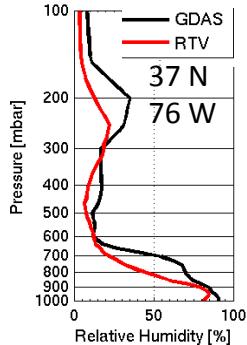
## ***Radiosonde Observations (10): 19 (17 Z)- 21 (00Z) April 2012)***



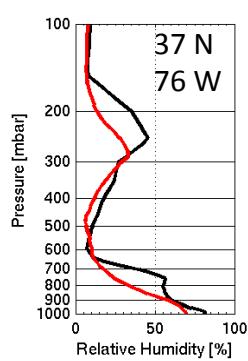
# GRASP Validation Campaign (April 20, 2012)



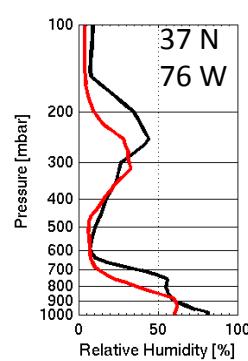
IASI-01:30 UT



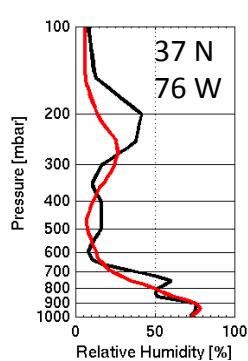
CrIS-06:10



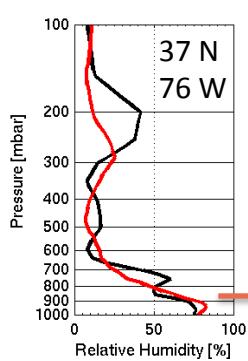
AIRS-07:11



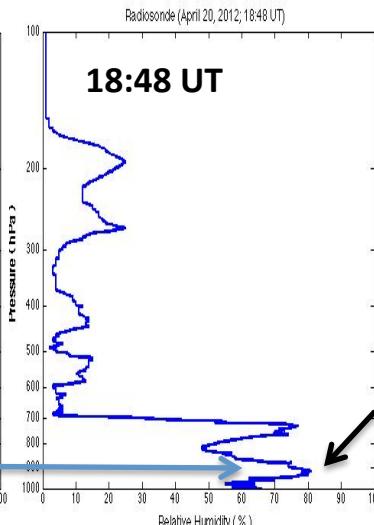
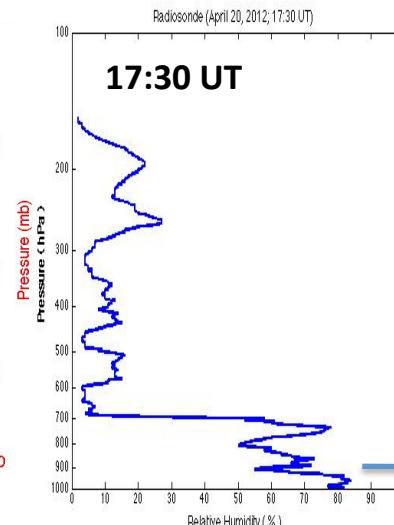
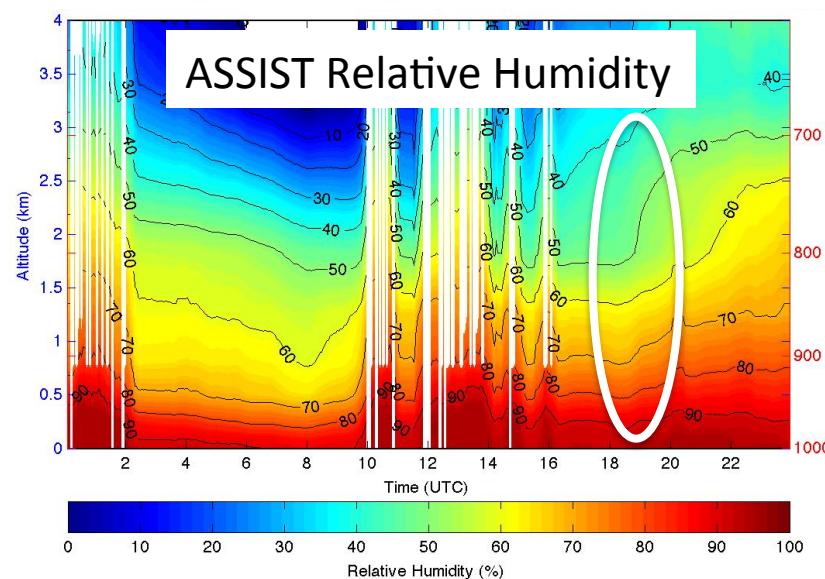
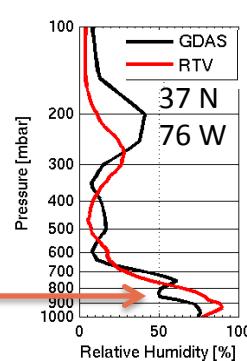
IASI-15:30



CrIS-17:30



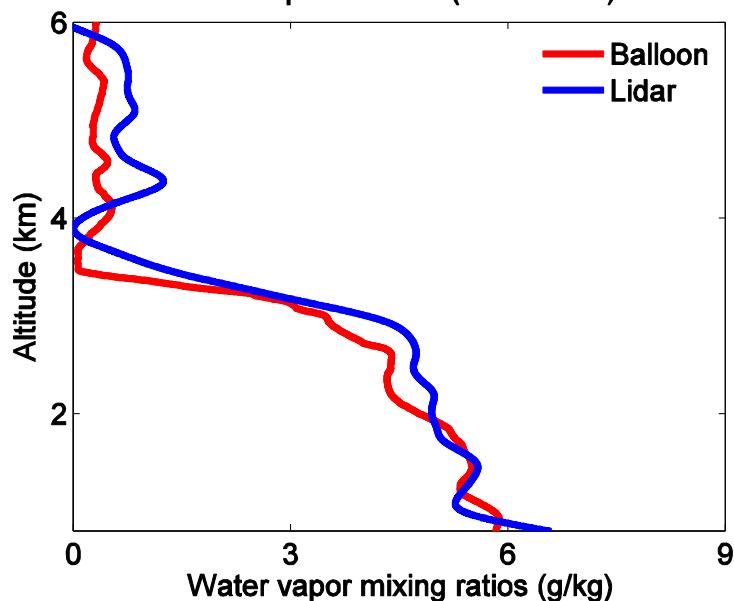
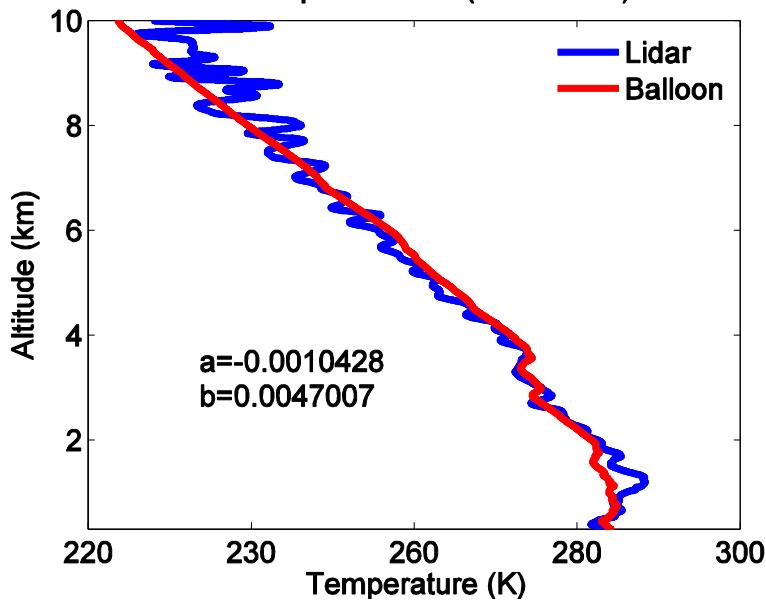
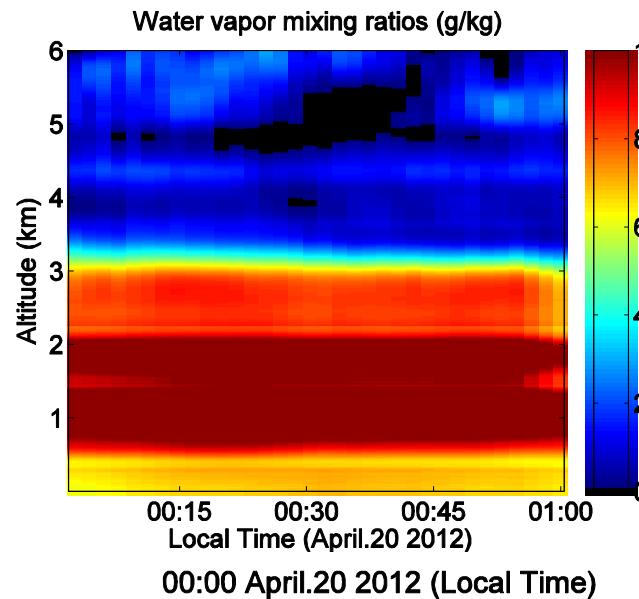
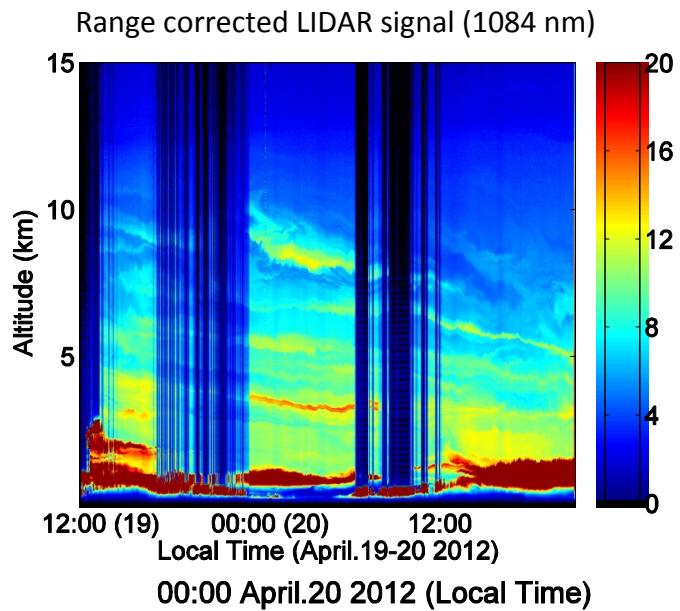
AIRS-18:17 UT



AIRS-CrIS  
Moisture  
Change  
Verified  
by Raob &  
ASSIST

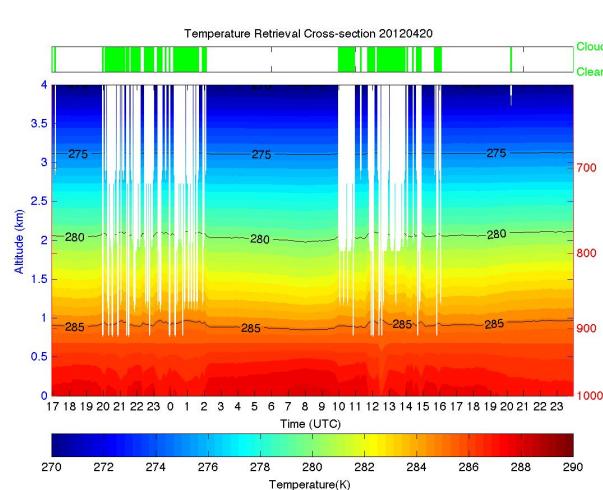
Radiosonde Relative Humidity

# GRASP April 20, 2012: Raman Lidar



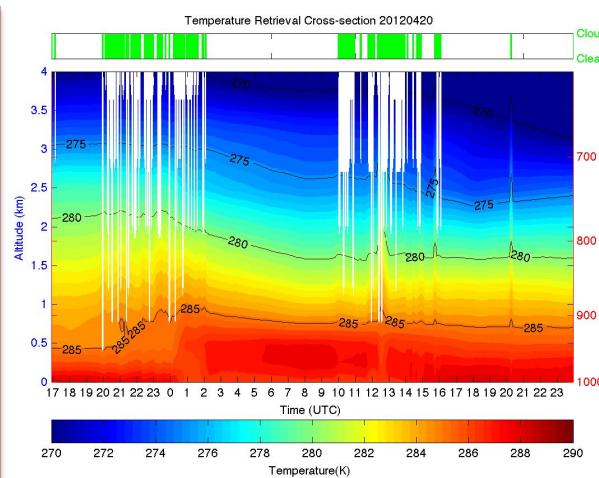
# ASSIST Profile Results

## April 19 17 UTC – April 21, 00 UTC

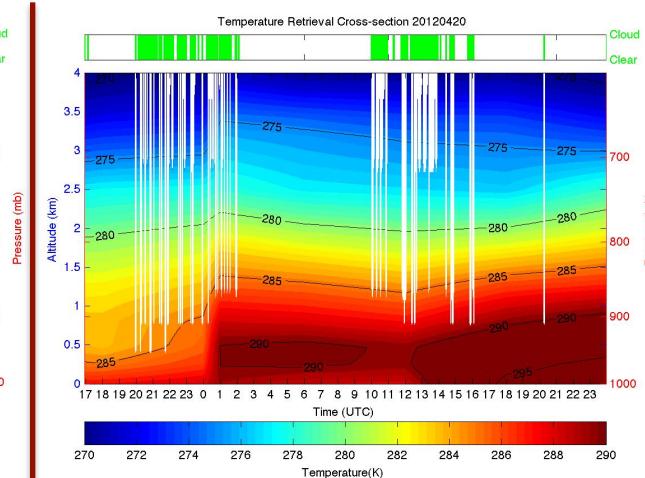


ASSIST - only

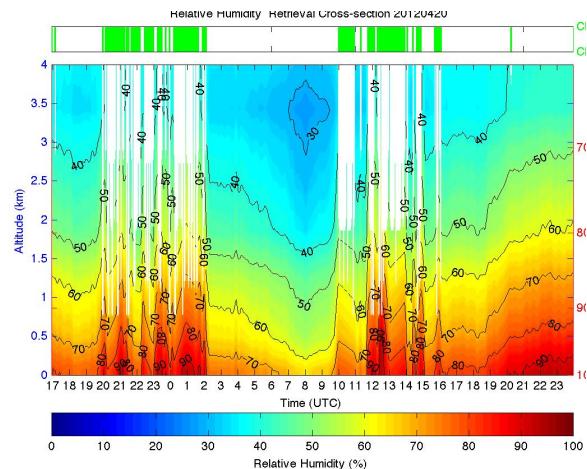
### Temperature ( 0 – 4 km)



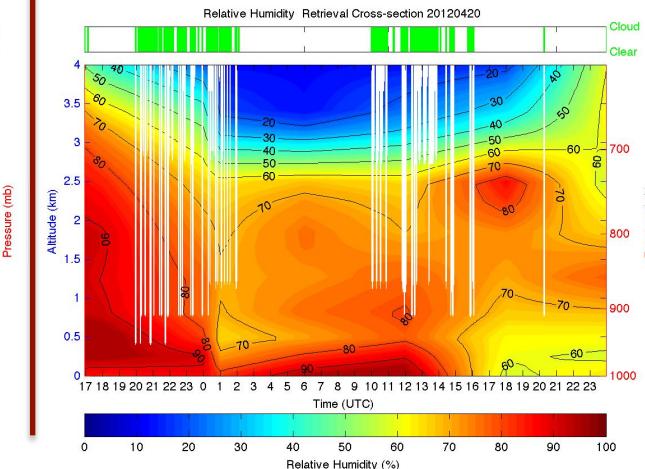
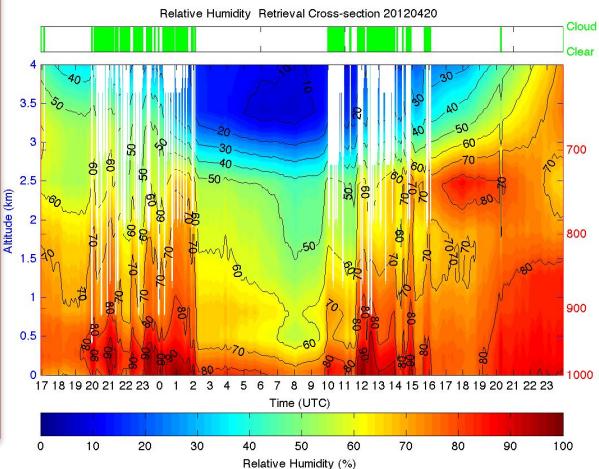
ASSIST w RAQMS



RAQMS

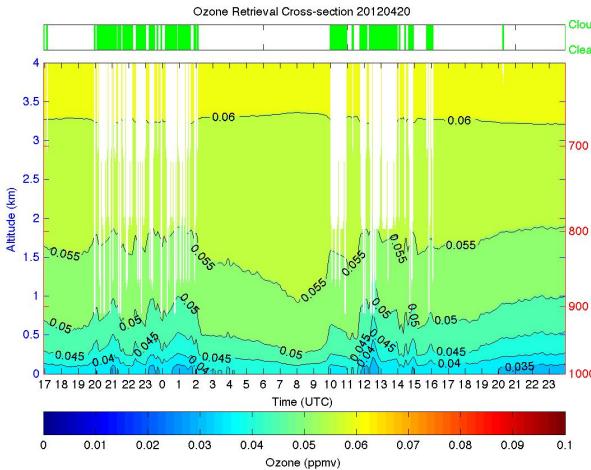


### Relative Humidity ( 0 – 4 km)

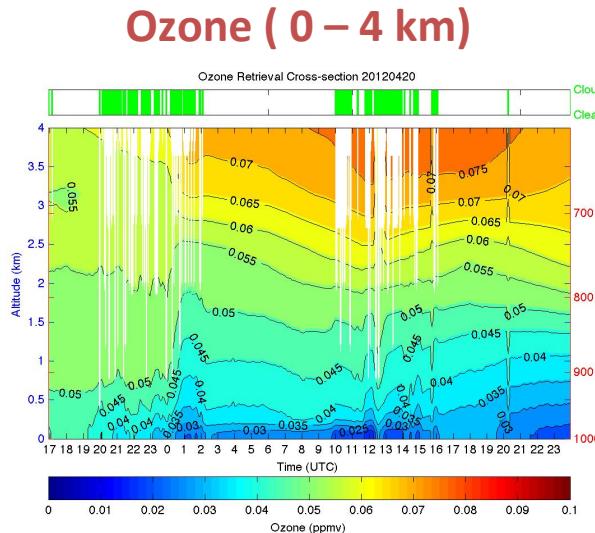
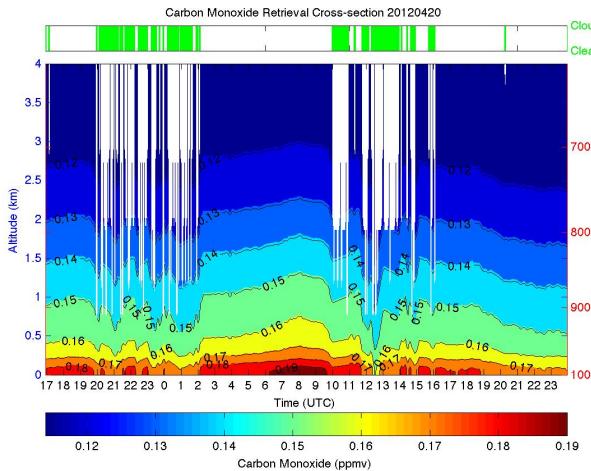


# ASSIST Profile Results

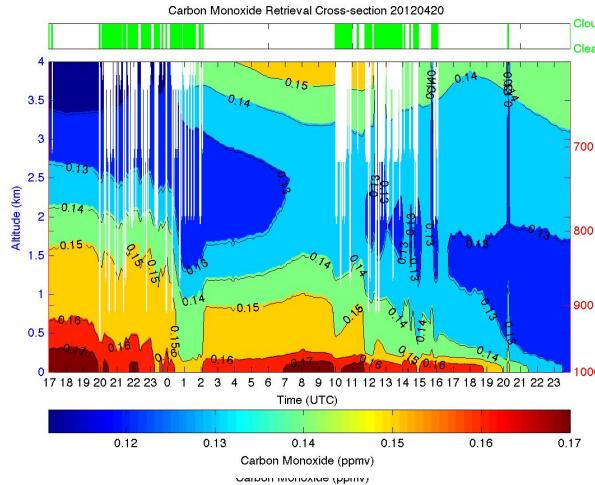
## April 19 17 UTC – April 21, 00 UTC



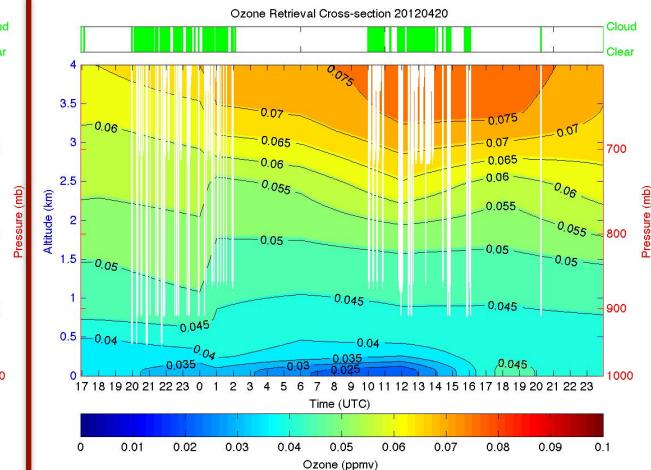
ASSIST - only



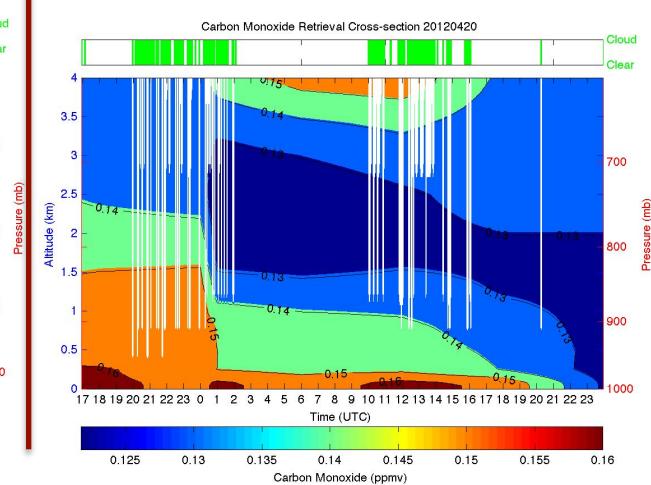
ASSIST w RAQMS



Carbon Monoxide( 0 – 4 km)

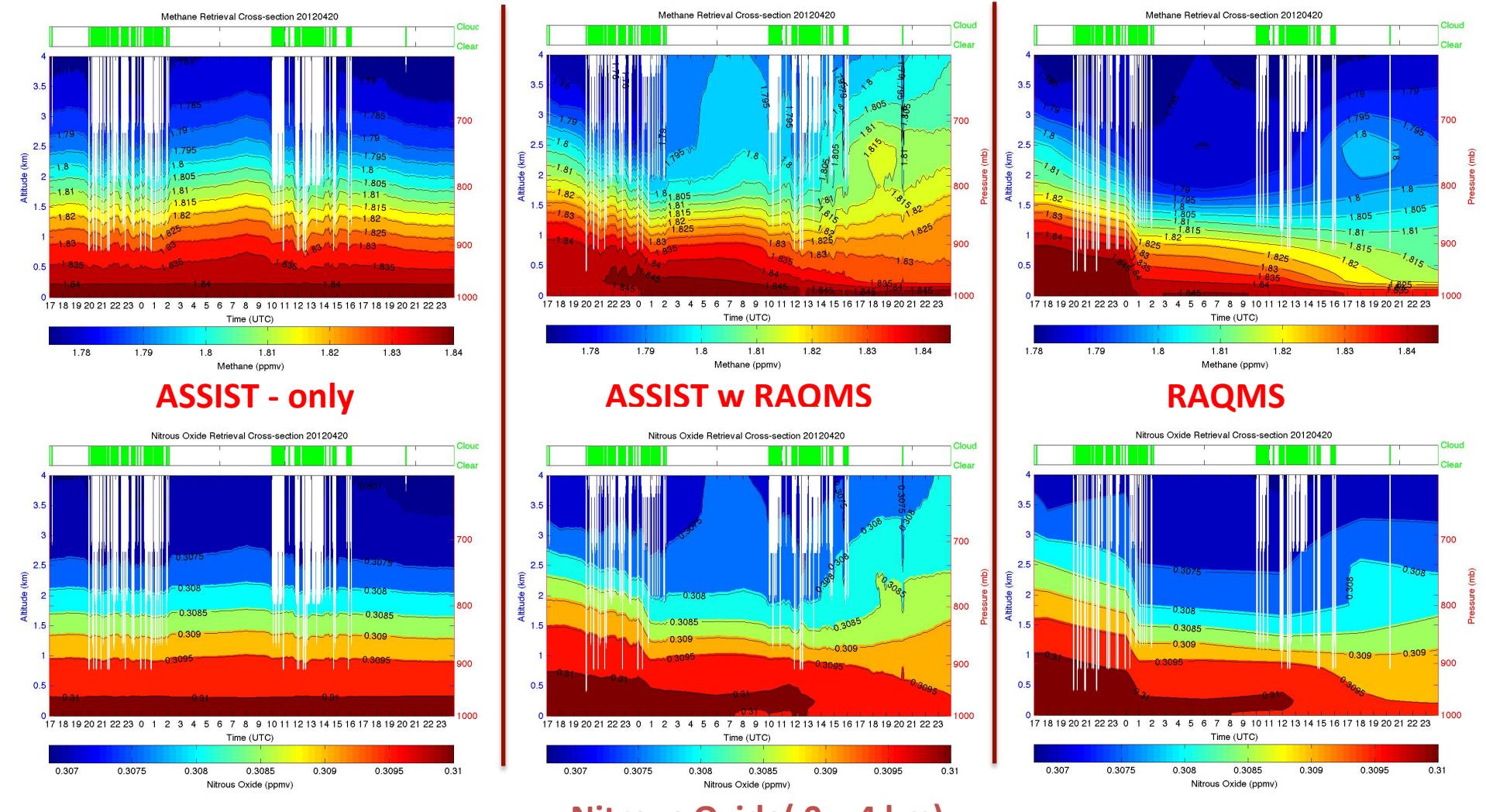


RAQMS



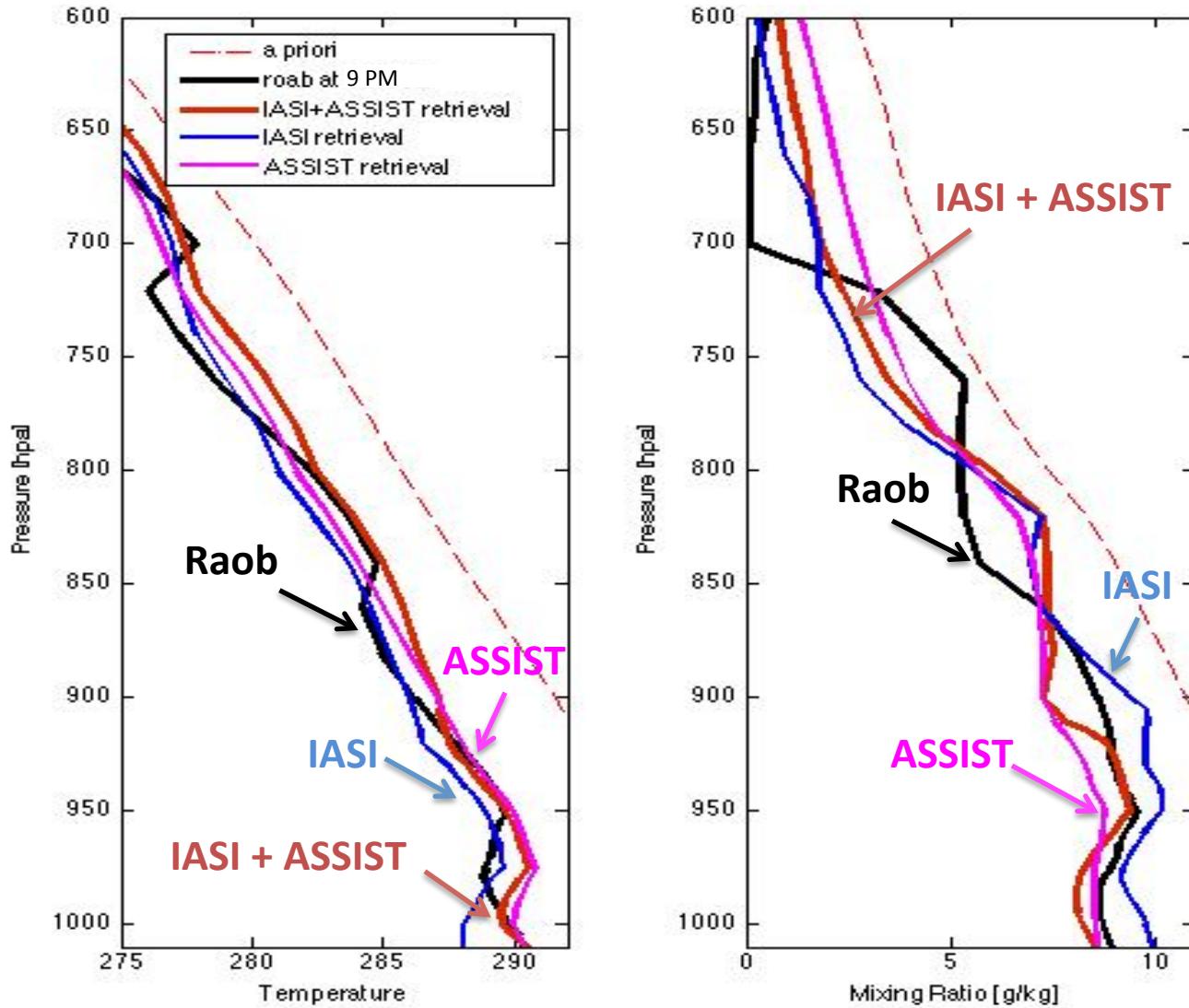
# ASSIST Profile Results

## April 19 17 UTC – April 21, 00 UTC

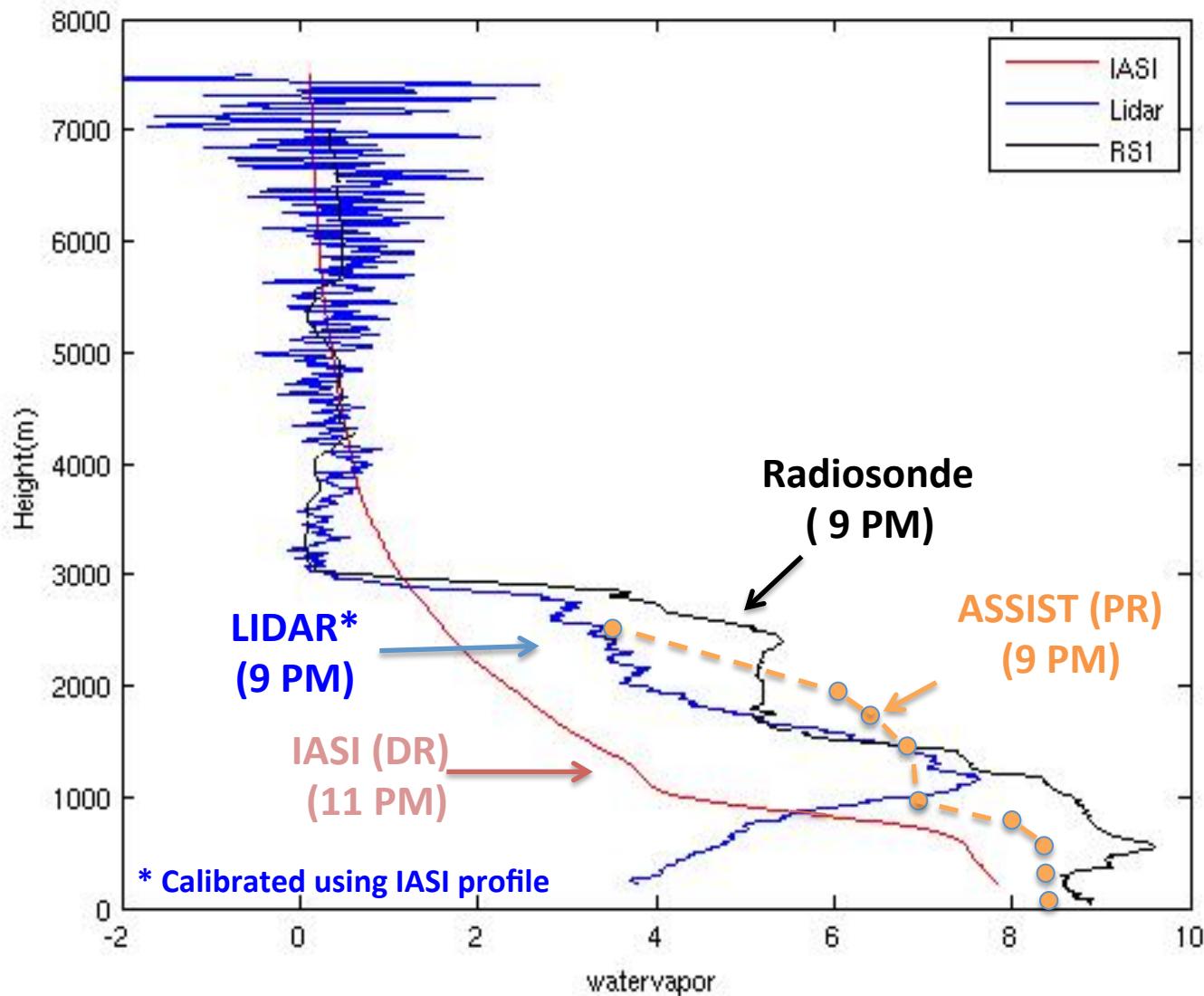


# ASSIST + Satellite (April 20, 2012)

Physical Regression (PR) Retrieval for IASI (11 PM) and ASSIST (9 PM) on 20120420



# Raman Lidar (April 20, 2012)



# Summary

- A unique in-situ and remote sensing data set has been collected during the HU/UW Ground-based Remote Atmospheric Sounding Project (GRASP) satellite ultraspectral sounding validation campaign
- It is shown that ground based FTS and Raman Lidar data can be used to validate satellite tropospheric soundings with an accuracy close to that provided by radiosonde observations
- The GRASP satellite and ground based data set is to be made available to the research community for remote sensing algorithm development and validation.

*Thank you for listening*

*We greatly appreciate our GRASP campaign sponsors: DOE, NASA, NOAA, US Army*